# Modeling 13 Archimedean solids by an object-oriented language<sup>o</sup>

# Modelado de los 13 sólidos de Arquímedes con un lenguaje de programación orientado a objetos

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**ABSTRACT:** The computational study of structures with chemical relevance is preceded by its modeling in such manner that no calculations can be submitted without the knowledge of their spatial atomic arrangement. In this regard, the use of an object-oriented language can be helpful both to generate the Cartesian coordinates (.xyz file format) and to obtain a ray-traced image. The modeling of chemical structures based on programming has some advantages with respect to other known strategies. The more important advantage is the generation of Cartesian coordinates that can be visualized easily by using free of charge software. Our approach facilitates the spatial vision of complex structures and make tangible the chemistry concepts delivered in the classroom. In this article an undergraduate project is described in which students generate the Cartesian coordinates of 13 Archimedean solids based on a geometrical/programming approach. Students were guided along the project and meetings were held to integrate their ideas in a few lines of programmed codes. They improved their decision-making process and their organization and collecting information capabilities, as much as their reasoning and spatial depth. The final products of this project are the coded algorithms and those made tangible the grade of learning/ understanding derived of this activity.

KEYWORDS: Archimedean solids, pov-ray, programming, geometrical study, modeling.

**RESUMEN:** El estudio computacional de estructuras con relevancia en la química es precedido por el modelado de las mismas; no se pueden realizar cálculos sin el conocimiento del arreglo espacial atómico. El uso de un lenguaje de programación orientado a objetos ayuda a generar las coordenadas cartesianas (archivos .xyz) y obtener una imagen a partir de un modelo 3D. El modelado de estructuras químicas basadas en programación tiene algunas ventajas respecto a otras estrategias conocidas. La mayor ventaja es la generación de coordenadas que pueden ser visualizadas fácilmente usando un *software* libre. Nuestro enfoque facilita la visión espacial de estructuras complejas y hace entendibles los conceptos de química vistos en clase. En este

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artículo describimos un proyecto desarrollado por estudiantes de licenciatura en el cual obtuvieron las coordenadas cartesianas de los 13 sólidos de Arquímedes, usando un enfoque geométrico y de programación. Los estudiantes fueron orientados a lo largo del proyecto, se realizaron reuniones para compartir ideas y códigos con pocas líneas. También mejoraron la toma de decisiones y su ejecución, sus capacidades para organizar y reunir información, así como su razonamiento y profundidad espacial. El producto final de este proyecto son los algoritmos codificados y el aprendizaje y entendimiento derivado de esta actividad.

PALABRAS CLAVE: sólidos de Arquímedes, *pov-ray*, programación, estudio geométrico, modelado.

# Introduction

The importance of the study of nanostructures with chemical relevance based on regular shapes relies on the gain of a simple vision or explanation of their featured complexity (i.e., metal clusters, metal-organic frameworks, complex metallic alloys, and so on). The process of structural simplification can be fueled by using symmetry elements, and the visualization might be facilitated by an object-oriented language. In materials science and structural chemistry, the spatial vision is recognized as valuable in the understanding of bonding and structure. Certainly, the training of second-year undergraduate students requires the use of programming tools to facilitate the assimilation of concepts as topology, bonding, and all covered subjects in materials chemistry and computational chemistry courses (Morales-Vidales et al., 2020). In other words, the study of regular shapes is inherent to structural chemistry, where a simplification of complex structures is done by using polyhedral building blocks. In literature the use of regular shapes to describe the bonding in Boron clusters is plenty and they have been modeled/determined with octahedral and tetrahedral symmetries (Hayami and Otani, 2011; Wang, 2016). Interestingly, the snub Archimedean solids (snub cube and snub dodecahedron) features the property of chirality depending on the direction of applied rotation. For example, the B60 molecule was proposed as a chiral distorted snub dodecahedron (Zope y Baruah, 2011). Another interesting systems displaying regular shapes (Platonic, Archimedean and Catalan solids) are gold nanoparticles whose morphology depends on the content of water and a capping agent known as poly(vinyl pyrrolidone) (Kim et al., 2010). The Archimedean solids have also been realized as candidates of carbon structures, and the proposal of a  $C_{120}$  molecule based on the truncated icosidodecahedron was reported in 1985 (Haymet, 1985). Other amazing structures were explained in terms of concentric shells describing dodecahedron and icosidodecahedron polyhedral shapes (Kong et al., 2007; Niu et al., 2014). However the truncated octahedron (Ni *et al.*, 2005), truncated tetrahedron (Leininger et al., 2000), truncated cuboctahedron (Eddaoundi et al., 2001), cuboctahedron (Tomiaga et al., 2004), Rhombicuboctahedron (Qui et al., 2019), and snub cube (Xiong et al, 2010; Gupta and Corbett, 2012; Hudson, 2010) have also been reported.



The study of the coordination number in face centered cubic (FCC) gold structures, grant us with the first sight of an Archimedean solid; the cuboc-tahedron which is formed among 12 first neighbors linked to one central atom (figure 1a). Second neighbor's analysis of the gold atoms arrangement (figure 1b), let us visualize the shape of an octahedron with surrounding atoms located at the cell parameter value (approx. acube = 4.07 Å). Further analysis shows us another fascinating atomic arrangement: a distorted rhombicuboctahedron formed by 24 neighboring atoms, which are located at circa 4.98 Å (acube\*sqrt (6)/2 distance value). More recently, it was reported that the thiolated gold clusters can be described using distorted tetrahedron and octahedron building blocks. It attests the distortion induced by the sulfur atoms to the gold-gold bonds with the size reduction on clusters. The polyhedral approach is interesting because it maintains the idea of compactness when it refers to metal clusters (Tlahuice-Flores, 2019).

The literature related to geometrical studies of metal clusters included cuboctahedron, icosahedron, body centered cubic and simple cubic structures providing us with formulas to determine the number of constituting atoms, coordination numbers and so on (Montejano-Carrizales, 1997). Recently, some of us have published the study of  $Au_{60}$  cluster modeled as one snub dodecahedron in its neutral charge state. Obtaining degenerated frontier orbitals in accordance with its displayed I-symmetry (Jacobo-Fernández *et al.*, 2021). This example, clearly attests the importance of an orientated to objects code to facilitate the generation of cartesian coordinates of structures with chemical relevance, being this the first step to simulate related structures.

In this article, we describe a project devoted to the study of 13 Archimedean solids carried out by undergraduate students; the used methodology is described, and the obtained results are summarized.

**Figure 1.** (a) The nearest 12 neighbors in a metal with FCC structure are displayed. Central atom (in green color) is surrounded by atoms (in red color) describing a cuboctahedron. (b) Second neighbors in FCC structure are forming an octahedral arrangement. (c) The distorted rhombicuboctahedron arrangement of 24 third neighbors are shown. The rest of the atoms forming the FCC structure are displayed in glass texture.



### Archimedean solids and their construction

It is important to know that Archimedean solids were named after Archimedes work (287-212 BCE). There are 13 Archimedean solids and they can be constructed from the Platonic solids. Each Archimedean solid is comprised by same type of regular faces sharing common vertices; thus, each vertex is linked to the same type of faces, and it looks similar from a close-up view. Moreover, only Platonic solids containing triangular faces (tetrahedron, icosahedron and octahedron) can produce three of the Archimedean solids by truncation of one third of their edges (truncated icosahedron, truncated octahedron, truncated tetrahedron). In the case of truncation at the middle point of the Platonic solid edges, the icosidodecahedron (starting from the icosahedron/dodecahedron) and the cuboctahedron (from the cube) are generated. The other eight Archimedean solids require correction operations such as translation (truncated cube, truncated cuboctahedron, rhombicuboctahedron, rhombicosidodecahedron, truncated icosidodecahedron, and truncated dodecahedron) (Ball and Coxeter, 1987) and rotation of their faces to produce the same length of their edges (snub cube and snub dodecahedron) (Wells, 1991).

# Methodology

We started our study by proposing new algorithms in the Pov-Ray<sup>1</sup> language to model the 13 Archimedean solids. Pov-Ray is a powerful tool to code related mathematical algorithms and to generate 3D models (initial configurations). In this opportunity, our programmed truncation algorithms to model Platonic solids were not enough and new algorithms to select, translate and rotate faces were implemented. Such algorithms were used to correct the truncated structures sustaining not equal edge lengths (table 1). With respect to Pov-Ray codes, the use of macros was mandatory to reduce the repetition of code lines and to reduce the size of related programs. An introductory use of macros is provided in the supporting information with one example. In table 2 are included geometrical features of 13 Archimedean solids.

It is important to mention that the truncated octahedron is the unique Archimedean solid whose repetition in the space can fill it with no gaps. In solid state this shape is assumed by the Wigner Seitz cell of FCC structure (Kittel, 1996).

# Learning objetives

In this project, second year undergraduate students were devoted to the geometrical study of Archimedean solids and their relationship with Platonic so-

<sup>&</sup>lt;sup>1</sup> http://www.povray.org



Archimedean solid	From the Archimedean/ Platonic solid	Operation
Cuboctahedron	Cube/Octahedron	Truncation of edges in two equal parts
Truncated cube	Cuboctahedron Cube	Perpendicular translation of triangular faces Irregular truncation of square faces
Truncated cuboctahedron	Truncated cube/ Cuboctahedron/ Rhombicuboctahedron	Truncation of triangular faces and translation/truncation in three equal parts of the triangular faces and translation/ translation outwards of square faces
Rhombicuboctahedron	Cube/Octahedron/ Cuboctahedron	Perpendicular translation of square faces/perpendicular translation of triangular faces/Truncation of edges in two equal parts
Snub cube	Rhombicuboctahedron	Rotation of square faces of rhombicuboctahedron
Rhombicosidodecahedron	Dodecahedron/ Icosahedron	Translation of dodecahedron/ icosahedron faces
Snub dodecahedron	Rhombicosidodecahedron	Rotation of pentagonal faces of rhombicosidodecahedron
Truncated tetrahedron	Tetrahedron	Truncation of edges in three equal parts
Truncated octahedron	Octahedron	Truncation of edges in three equal parts
Truncated icosahedron	Icosahedron	Truncation of edges in three equal parts
Truncated icosidodecahedron	Icosidodecahedron/ Truncated dodecahedron/ Truncated Icosahedron	Truncation and translation of hexagonal faces/translation of decagons/ translation of hexagonal faces
Truncated dodecahedron	Dodecahedron/ Icosidodecahedron	Irregular truncation and perpendicular translation of triangular faces/ translation of triangular faces
Icosidodecahedron	Dodecahedron/ Icosahedron	Truncation of edges in two equal parts

 Table 1. Description of the used operations to produce the Archimedean solids starting from related

 either Archimedean or Platonic solids.

Source: Author's elaboration.

lids. All the obtained models can be considered as part of their training to further study of electronic properties of nanostructures of boron, carbon or gold.

As part of this project, students learnt about translation and rotation operations to generate some of 13 Archimedean solids. They applied their previous knowledge on an object-oriented language with the goal of generate new irregular solids. All the work is oriented to model chemical structures with relevance in areas as materials science. In the process, it was necessary to introduce the use of macros to reduce/adapt the code included in this publication. The effectiveness and compliance of our project goals is corroborated by the final written reports, the discussion of algorithms and the final codes herein delivered.



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Archimedean solid	Type of face	Number of faces	Number of edges	Number of vertices
Cuboctahedron	8 triangles; 6 squares	14	24	12
Truncated cube	8 triangles; 6 octagons	14	36	24
Truncated cuboctahedron	12 squares; 8 hexagons; 6 octagons	26	72	48
Rhombicuboctahedron	8 triangles; 18 squares	26	48	24
Snub cube	32 triangles; 6 squares	38	60	24
Rhombicosidodecahedron	20 triangles; 30 squares; 12 pentagons	62	120	60
Snub dodecahedron	80 triangles; 12 pentagons	92	150	60
Truncated tetrahedron	4 triangles; 4 hexagons	8	18	12
Truncated octahedron	6 squares; 8 hexagons	14	36	24
Truncated icosahedron	12 pentagons; 20 hexagons	32	90	60
Truncated icosidodecahedron	30 squares; 20 hexagons; 12 decagons	62	180	120
Truncated dodecahedron	20 triangles; 12 decagons	32	90	60
Icosidodecahedron	20 triangles; 12 pentagons	32	60	30

#### Table 2. Geometrical features of 13 Archimedean solids.

Source: Author's elaboration.

### Conceptual orientation Operations to generate Archimedean solids

The modeling of various Archimedean solids was based on the implementation of new algorithms to make some operations as:

- 1. Selection of regular faces. It implies to find each perpendicular vector to every face of the solid. The use of cross vector/dot product operation among two vectors sharing a vertex and forming a pair of edges was necessary. The centered cube (centered at 0,0,0) is related to various Archimedean solids whose perpendicular vectors are directed along the cube diagonals.
- 2. *Translation of selected faces.* It is obtained by adding a perpendicular vector to each vertex forming a face. For example, this operation produces the perpendicular displacement (k) applied to the square faces of the cube to produce the rhombicuboctahedron.
- 3. *Rotation of selected faces.* It is easily done by using the perpendicular vector to each face and finding numerically the proper rotation angle.
- 4. Location of vertices along one edge where no regular truncation is possible. This operation was implemented as a macro and it yields the proportional displacement to truncate the Platonic solids in order to obtain 5 of the 13 Archimedean solids.



It is important to note that various of the parameters used to build the Archimedean solids were calculated numerically, for example, in the case of the rhombicuboctahedron, the calculation of the magnitude of the perpendicular vector (k) to one square face of the cube was done by adding up a fraction of the perpendicular vector to each vertex of the cube and the distance among the translated positions was used to stop the search.

#### The use of macros in an object-oriented programming language

The use of macros is recommended when there exist lines that are repeated through the code. The syntaxis to declare a macro is defined in the Box 1. Tokens refer to any number of Pov-Ray keywords, or punctuation marks which are the body of the macro. In such manner that it contains the code that is repeated, and it is pretended to replace it. In the supporting information is given an example of a macro.

Box 1. Commands in Pov-Ray Language to declare a Macro
#macro Identifier (parameters)
Tokens
#end

#### The algorithm to make an irregular truncation

In table 2 are found 5 Archimedean solids whose names include the word truncated. Among them, the truncated tetrahedron, truncated octahedron, and truncated icosahedron are obtained by a regular truncation (truncation of one third of their edges) of the related Platonic solids. Conversely, the truncated cube and truncated dodecahedron, cannot be truncated in an easy form and one new algorithm was proposed to make this possible. In the following is explained the algorithm used to truncate 5 Platonic solids and to obtain related Archimedean solids. In addition, in figure 2 is illustrated the algorithm.

- 1. Location of three points P1, P2 and P3 forming a pair of equal edges with a common vertex (P1).
- 2. Calculation of a pair of vectors: V1 = P3-P1 and V2 = P2-P1 to define the direction of the displacement.
- 3. Two new positions P4 and P5 are created along the V1 vector and one position P6 along the V2 vector. Look at figure 2a.
- Translation of the P4 and P5 positions resulting in TP4 = P1+h\*V1 and TP5 = P3- h\*V1, being h the magnitude of the displacement.
- 5. Translation of the P6 position by using TP6 =  $P1+h^*V2$ .
- 6. Calculation of the distance among translated point TP4 and TP6. When distance among TP6 and TP4 equals the distance among TP4 and TP5, the displacement is known, and it represents the proportion of truncation. See figure 2b for a final look of the algorithm.



The algorithm can be easily implemented for solids with edges forming an angle different of 90° used in figure 2.

**Figure 2.** The illustration of the algorithm used to truncate five Platonic solids and to generate the related Archimedean solids. (a) It starts with three vertices and two edges sharing a common vertex (P1) and placing a pair of new vertices (P5 and P4) along the direction given by the vector P2-P1. The position along the P3-P1 edge is used to conditionate the small displacement applied to P4 and P5 vertices. (b) The correct displacement is reached when the distance among TP6 and TP4 equals the distance in the other edge (TP4-TP5).



Source: Author's elaboration.

The given algorithm was coded as a macro and in the Box 2 is delivered.

```
Box 2. Macro for an irregular truncation of Platonic solid
edges. It determines the displacement to be applied to
vertices forming the truncated Archimedean solids
#macro Found_inc(Angle)
#declare P1=<0,0,0>;
#declare P2=<1,0,0>;
#declare P3=vaxis_rotate(P2,<0,0,1>,Angle);
#declare P4=P1;
#declare P5=P2;
#declare P6=P1;
#declare inc=0.27;
#declare h=0.00001;
#declare Cad="Au ";
#while (VDist(P4,P5)>VDist(P4,P6))
 #declare P4=inc*P2;
 #declare P5=(1-inc)*P2;
 #declare P6=inc*P3:
 #declare inc=inc+h;
#end
#end
```

# **Results and discussions**

The Archimedean solids can be generated starting from various related polyhedral solids as can be seen in table 1. In the next section, we discuss about the chosen path and the algorithm; also, we provide the programmed codes of each Archimedean solid.

#### The truncated tetrahedron from tetrahedron

The truncated tetrahedron consists of 4 hexagons, 4 triangles, 12 vertices and 18 edges. Despite the regular truncation is done by reducing the original



tetrahedron edge to one third, we proved the effectiveness of our proposed algorithm by finding the same proportion. See figure 3 for the structure, and the code is given in Box 3.

Figure 3. Truncated tetrahedron obtained by using the macro included in Box 2. Thin cylinders correspond with the parent tetrahedron



```
Box 3. POV-Ray code to make a truncated cube
// Insert here the last definition of libraries,
// light_source, camera, and background
#declare Pos= array[8]; // Cube positions
#declare TC= array [24]; // Truncated cube vertices
#declare acube=1;
                         // Cube edges length
#declare Pos[0]= <acube/2, acube/2, acube/2>;
#declare Pos[1]= <-acube/2, -acube/2, -acube/2>;
#declare Pos[2]= <-acube/2, acube/2, acube/2>;
#declare Pos[3]= <acube/2, -acube/2, acube/2>;
#declare Pos[4]= <acube/2, acube/2, -acube/2>;
#declare Pos[5]= <-acube/2, -acube/2, acube/2>;
#declare Pos[6]= <-acube/2, acube/2, -acube/2>;
#declare Pos[7]= <acube/2, -acube/2, -acube/2>;
#declare L=acube+0.1;
#fopen CT "TruncatedCube.xyz" write
Found inc(90)
//Call the macro to know the fraction to truncate the
    square face.
 #declare cont=0;
#declare i=0:
#while(i<7)
#declare j=i+1;
 #while (j<8)
 #declare Distan=VDist(Pos[i],Pos[j]);
 #declare Desp=Pos[j]-Pos[i];
 #if(Distan<L)
 #declare TC[cont ]=Pos[i]+inc*Desp;
 #declare TC[cont+1]=Pos[i]+(1-inc)*Desp;
//There are 2 points in the edge: the closer to Pos[i] and
    the closer to Pos[j]
#write (CT,"Au", " ",vstr(3, TC[cont ]," ",3,5),"\n")
#write (CT,"Au", " ",vstr(3, TC[cont+1]," ",3,5),"\n")
 sphere{TC[cont],0.2 texture {pigment{color Blue}}}
 sphere{TC[cont+1],0.2 texture {pigment{color Blue}}}
 #declare cont=cont+2;
 #end
 #declare j=j+1;
 #end
 #declare i=i+1;
#end
```



#### The truncated cube from cube

The truncated cube has 6 octagons, 8 triangles, 24 vertices and 36 edges. The truncation of cube is not regular, and the proportion of truncation was determined as approx. 0.293 times the cube edge length (Ni *et al.*, 2005). See figure 4 for the structure of the truncated tetrahedron, and its code is given in Box 4.

Figure 4. Truncated cube obtained with our proposed macro. Evidently the truncation is not regular, and it was necessary to implement a new algorithm (Box 2).



```
Box 4. POV-Ray code to make a truncated tetrahedron
// Insert here the last definition of libraries,
// light_source, camera, and background
//Insert here the macro to find the displacement of the
   tetrahedron positions
                          // Tetrahedron edges length
#declare atetra=1:
#declare L=atetra*sqrt(2)+0.1;
#declare PosTetra= array[4]; // Tetrahedron positions
#declare TT= array [12]; // Truncated tetrahedron vertices
#declare PosTetra[0]=<atetra/2, atetra/2, atetra/2>;
#declare PosTetra[1]=<-atetra/2, -atetra/2, atetra/2>;
#declare PosTetra[2]=<-atetra/2, atetra/2, -atetra/2>;
#declare PosTetra[3]=<atetra/2, -atetra/2, -atetra/2>;
#fopen TTf "TruncatedTetrahedron.xyz" write
Found_inc(60)
//Call the macro to know the proportion to truncate an
    equilateral triangular face.
#declare cont=0:
#declare i=0;
#while(i<3)
#declare j=i+1;
#while (j<4)
 #declare Distan=VDist(PosTetra[i],PosTetra[j]);
 #declare Desp=PosTetra[j]-PosTetra[i];
 #if(Distan<L)</pre>
 #declare TT[cont ]=PosTetra[i]+inc*Desp;
 #declare TT[cont+1]=PosTetra[i]+(1-inc)*Desp;
//There are 2 points in the edge: the closer to PosTetra[i]
    and the closer to PosTetra[j]
#write (TTf, "Au", " ", vstr(3, TT[cont ]," ", 3,5),"\n")
#write (TTf, "Au", " ", vstr(3, TT[cont+1]," ", 3,5),"\n")
 sphere{TT[cont],0.2 texture {pigment{color Blue}}}
 sphere{TT[cont+1],0.2 texture {pigment{color Blue}}}
 #declare cont=cont+2;
 #end
 #declare j=j+1;
#end
#declare i=i+1;
#end
```



#### The truncated octahedron from octahedron

The regular truncation of an octahedron results in the truncated octahedron. It shows 8 hexagons, and 6 squares; it has 24 vertices and 36 edges. See Box 5 for code, and figure 5 for the structure.

Figure 5. Truncated octahedron and its relationship with the octahedron. The truncation of the octahedron produces a truncated octahedron with an edge of one third of the original one.



Source: Author's elaboration.

Box 5. POV-Ray code to make a truncated octahedron // Insert here the last definition of libraries, // light source, camera, and background //Insert here the macro included in Box 2. #declare aoct=sqrt(2); // Octahedron edges length #declare L=aoct\*sqrt(2)/2+0.1; #declare PosOct= array[6]; // Octahedron positions #declare TO= array [24]; // Truncated tetrahedron vertices #declare PosOct[0]=<aoct/2, 0, 0>; #declare PosOct[1]=<-aoct /2, 0, 0>; #declare PosOct[2]=<0, aoct/2, 0>; #declare PosOct[3]=<0, -aoct/2, 0>; #declare PosOct[4]=<0, 0, aoct/2>; #declare PosOct[5]=<0, 0, -aoct/2>; #fopen TOf "TruncatedOctahedron.xyz" write Found\_inc(60) //Call the macro to find what fraction we have to translate in an equilateral triangular face. #declare cont=0; #declare i=0; #while(i<5) #declare j=i+1; #while (j<6) #declare Distan=VDist(PosOct[i],PosOct[j]); #declare Desp=PosOct[j]-PosOct[i]; #if(Distan<L) #declare TO[cont ]=PosOct[i]+inc\*Desp; #declare TO[cont+1]=PosOct[i]+(1-inc)\*Desp; //There are 2 points in the edge: the closer to PosOct[i] and the closer to PosOct[j] #write (TOf,"Au", " ",vstr(3, TO[cont ]," ",3,5),"\n")
#write (TOf,"Au", " ",vstr(3, TO[cont+1]," ",3,5),"\n") sphere{TO[cont],0.2 texture {pigment{color Blue}}} sphere{TO[cont+1],0.2 texture {pigment{color Blue}}} #declare cont=cont+2; #end #declare j=j+1; #end #declare i=i+1; #end



#### The truncated dodecahedron from dodecahedron

This Archimedean solid is comprised by 12 decagons, 20 triangles, 60 vertices and 90 edges. It can be obtained by an irregular truncation of the dodecahedron to form the decagons and to obtain the triangles. The fraction to truncate the pentagonal faces was calculated as 0.276 times the edge length of the dodecahedron. In Box 6 is provided the code to generate the truncated dodecahedron (figure 6) based on the macro showed in Box 2.

Figure 6. Truncated dodecahedron. The thin cylinders feature the edges of the original dodecahedron.



Source: Author's elaboration.

Box 6. POV-Ray code to make a truncated dodecahedron from dodecahedron // Insert here the last definition of libraries, // light\_source, camera, and background //Insert here the macro included in Box 2. #declare n=20: #declare dode=array[n] #declare acube=1; #declare L=0.7; #declare fi=(sqrt(5)-1)/2; // Dodecahedron vertices #declare dode[0]= (acube/2)\*<1+fi,0,fi>; #declare dode[1]= (acube/2)\*<-(1+fi),0,-fi>; #declare dode[2]= (acube/2)\*<1+fi,0,-fi>; #declare dode[3]= (acube/2)\*<-(1+fi),0,fi>; #declare dode[4]= (acube/2)\*<0.fi.1+fi>: #declare dode[5]= (acube/2)\*<0,fi,-(1+fi)>; #declare dode[6]= (acube/2)\*<0,-fi,1+fi>; #declare dode[7]= (acube/2)\*<0,-fi,-(1+fi)>;

#declare dode[5]= (acube/2)\*<0,fi,-(1+fi)>; #declare dode[6]= (acube/2)\*<0,-fi,1+fi>; #declare dode[7]= (acube/2)\*<0,-fi,-(1+fi)>; #declare dode[8]= (acube/2)\*<fi,1+fi,0>; #declare dode[9]= (acube/2)\*<fi,1+fi,0>; #declare dode[10]= (acube/2)\*<fi,(1+fi),0>; #declare dode[11]= (acube/2)\*<-fi,-(1+fi),0>; #declare dode[12]= (acube/2)\*<-fi,-(1+fi),0>; #declare dode[13]= (acube/2)\*<-1, 1, 1>; #declare dode[14]= (acube/2)\*<-1, 1, 1>; #declare dode[15]= (acube/2)\*<-1, 1, 1>; #declare dode[16]= (acube/2)\*<1, 1, -1>; #declare dode[16]= (acube/2)\*<1, 1, -1>; #declare dode[17]= (acube/2)\*<-1, 1, 1>; #declare dode[18]= (acube/2)\*<-1, 1, -1>; #declare dode[19]= (acube/2)\*<-1, 1, -1>; #fopen DTf "TruncatedDodecahedron.xyz" write Found\_inc(108) //Call the macro to find the truncation value over the edges of pentagonal faces. #declare cont=0; #declare PosT=array[60]; #declare i=0; #while(i<n-1) #declare j=i+1; #while (j<n) #declare Distan=VDist(dode[i],dode[j]); #declare Desp=dode[j]-dode[i]; #if(Distan<L) #declare PosT[cont]=dode[i]+inc\*Desp; #write (DTf,"Au", " ",vstr(3, PosT[cont]," ",3,5),"\n")
#write (DTf,"Au", " ",vstr(3, PosT[cont]," ",3,5),"\n") sphere { PosT[cont], 0.1 pigment{color Red} } #declare cont=cont+1; #declare PosT[cont]=dode[i]+(1-inc)\*Desp; sphere { PosT[cont], 0.1 pigment{color Red} } #declare cont=cont+1; #end #declare j=j+1; #end #declare i=i+1: #end



### The truncated icosahedron from icosahedron

In Chemistry, this is the most famous Archimedean solid given the fact that  $C_{60}$  molecule was confirmed experimentally (Kroto *et al.*, 1985). Just like the other two Platonic solids previously discussed (tetrahedron and octahedron) the icosahedron is formed only by 20 triangular faces. This means that truncated icosahedron, can be easily obtain by dividing the 30 edges of the icosahedron into three equal parts (two new positions located at each icosahedron edges). The structure of truncated icosahedron is depicted in figure 7 and the programmed code is given in Box 7.

**Figure 7.** Truncated icosahedron. The icosahedron edge is divided among three in such manner that the 30 edges generate the 60 vertices of this Archimedean solid. Thin cylinders represent the icosahedron edges.



Box 7. POV-Ray code to make a truncated icosahedron with length 1 // Insert here the last definition of libraries, // light_source, camera, and background #declare ico= array[12]; // Icosahedron positions #fopen ITf "TruncatedIcosahedron.xyz" write #declare fi=(sqrt(5)-1)/2; #declare acube=3/fi; // Icosahedron code acutes	<pre>#while (i<n-1) "="" ",="" ",3,5),"\n")="" #declare="" #if(="" #while="" #write="" (ico[j]-ico[i])="" (itf;"au",="" (j<n)="" 3;="" <="" ico[j]);="" icodist="VDist(ico[i]," icodist<="ladoIco+0.1)" icotrun[kc60]="ico[i]+" icotrun[kc60],"="" j="i+1;" pre="" vstr(3,=""></n-1)></pre>
<pre>#declare ico[0]= (acube/2)*&lt;1,0,f&gt;; #declare ico[1]= (acube/2)*&lt;1,0,f&gt;; #declare ico[2]= (acube/2)*&lt;1,0,f&gt;; #declare ico[3]= (acube/2)*&lt;0,f,1&gt;; #declare ico[5]= (acube/2)*&lt;0,f,1&gt;; #declare ico[6]= (acube/2)*&lt;0,f,1&gt;; #declare ico[7]= (acube/2)*&lt;0,f,1&gt;; #declare ico[7]= (acube/2)*&lt;0,f,1&gt;; #declare ico[7]= (acube/2)*&lt;0,f,1&gt;; #declare ico[9]= (acube/2)*&lt;0,f,1&gt;; #declare ico[9]= (acube/2)*&lt;0,f,1&gt;; #declare ico[9]= (acube/2)*<f,1,0>; #declare ico[1]= (acube/2)*<f,1,0>; #declare RIc=0.1; #declare RIc=0.1; #declare n=12; // vertices of icosahedron #declare ladoIco=acube*fi; #declare kC60=1; // counter #fopen Icotrunc "TruncatedIcosahedron.xyz" write #declare IcoTrun= array[60];</f,1,0></f,1,0></f,1,0></f,1,0></f,1,0></f,1,0></f,1,0></f,1,0></pre>	<pre>sphere {[coTrun [kC60], RIc pigment{color Cyan} finish{phong 1}} #write ([cotrunc,"Au", " ",vstr(3, IcoTrun [kC60],"     ",",",")             #declare IcoTrun[kC60]= ico[i]+ 2*(ico[j]- ico[i])/3;             sphere { IcoTrun [kC60], RIc pigment {color             Cyan} finish{phong 1}}             #write (Icotrunc,"Au", " ",vstr(3, IcoTrun [kC60],"             ",",")             #declare kC60=kC60+1;             #end             #declare i=i+1;             #end</pre>



#### The cuboctahedron from a cube

It has 8 triangular and 6 square faces with 12 vertices. It is obtained by dividing the cube edges (acube = 1) in two halves. The position vectors of the cube vertices are perpendicular to the triangular faces while the unitary i, j, and k vectors are perpendicular to its square faces. The edge length of cuboc-tahedron equals sqrt (2)/2. Figure 8 shows the cuboctahedron and its relationship with the cube.

**Figure 8.** A cuboctahedron obtained by truncation of the cube edges. The cuboctahedron edges have a length of sqrt (2)/2. The thin cylinders feature the parent cube.



Source: Author's elaboration.

$$\vec{P1}_{cuboctahedron} = \vec{P1}_{cube} + \frac{\vec{P2}_{cube} - \vec{P1}_{cube}}{2}$$
(1)

The algorithm to truncate the cube edges in two halves is given by the formula 1, which is used to obtain the positions of the cuboctahedron. Box 8 contains the programmed code to obtain the cuboctahedron from the cube and it implies to calculate the middle point among a pair of vertices separated by the length of the cube (acube).

Box 8. POV-Ray code to make a cuboctahedron // Insert here the last definition of libraries, // light_source, camera, and background #declare acube=2/sqrt(2); //cube edges length #declare Pos= array[8]; // cube positions	<pre>#while (j<n) #declare="" #if(l<="" 0.25="" acube+0.1)="" cuboc[ncub]="Pos[i]+0.5*(Pos[j]-" l="VDist(Pos[i],Pos[j]);" pigment{color="" pos[i]);="" pre="" red}}<="" sphere{cuboc[ncub],=""></n)></pre>
#declare cuboc= array [12]; // cuboctahedron vertices	<pre>#write (cubot,"Au", ", vstr(3, cubot[ncub]," ",3,5),"\n") #declare ncub=ncub+1;</pre>
// Cube positions (Box 3)	#end #declare j=j+1;
#fopen cuboct "cuboctahedron.xyz" write	#end #declare i=i+1;
// This block is to calculate the distances among vertices // and to define edges	#end
<pre>//Calculating the center of cube edges #declare i=0;</pre>	
#declare ncub=0;	
#declare n=8; #while (i <n-1)< td=""><td></td></n-1)<>	
#declare j=i+1;	



#### The icosidodecahedron from the icosahedron

This solid has 32 faces, 20 of them are triangles and 12 are pentagons. It has 30 vertices and 60 edges (figure 9). Just like the cuboctahedron, which can be obtain both from the cube or its dual (the octahedron) the icosidodecahedron can be obtain by locating a vertex in the middle point of the edges of either the dodecahedron or its dual. In other words, the icosidodecahedron is obtained by regular truncation of the icosahedron edges. In such manner that we can reuse the code to obtain the cuboctahedron. However, the initial vertices, will form the icosahedron instead of a cube. Evidently, formula 1 is also applied to this code (see Box 9).

**Figure 9.** Icosidodecahedron. It was obtained by finding the middle point of the icosahedron edges. The thin and blue sticks correspond with the icosahedron.



<pre>Box 9. POV-Ray code to make an icosidodecahedron // Insert here the last definition of libraries, // light_source, camera, and background #declare ico= array[12]; // Icosahedron positions #declare icosi= array [30]; // Icosidodecahedron vertices #declare acube=1*fi; //Icosahedron edges #fopen Icf "Icosidodecahedron.xyz" write // Icosahedron coordinates #declare ico[1]= (acube/2)*&lt;1,0,fi&gt;; #declare ico[2]= (acube/2)*&lt;1,0,fi&gt;; #declare ico[2]= (acube/2)*&lt;1,0,fi&gt;; #declare ico[3]= (acube/2)*&lt;1,0,fi&gt;; #declare ico[3]= (acube/2)*&lt;1,0,fi&gt;; #declare ico[4]= (acube/2)*&lt;0,fi,1&gt;; #declare ico[5]= (acube/2)*&lt;0,fi,1&gt;; #declare ico[6]= (acube/2)*&lt;0,fi,1&gt;; #declare ico[6]= (acube/2)*&lt;0,fi,-1&gt;; #declare ico[6]= (acube/2)*&lt;6,fi,1&gt;; #declare ico[8]= (acube/2)*&lt;6,fi,-1&gt;; #declare ico[1]= (acube/2)*&lt;6,fi,-1,0&gt;; #declare ico[1]= (acube/2)*&lt;6,fi,-1,0&gt;; #declare ico[1]= (acube/2)*&lt;<fi,-1,0>; #declare ico[1]= (acube/2)*&lt;<fi,-1< th=""><th><pre>#declare j=i+1; #while (j:n) #declare L= VDist(ico[i],ico[j]); #if(L&lt;1adoIco+0.1) #declare icosi[nicos]=ico[i]+0.5*(ico[j]-ico[i]); #write (Icf, Au", " ",vstr(3, icosi[nicos]," ",3,5),"\n") sphere{(icosi[nicos], 0.25 pigment{color Red}} #declare nicos=nicos+1; #end #declare j=j+1; #end #declare i=i+1; #end</pre></th></fi,-1<></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></fi,-1,0></pre>	<pre>#declare j=i+1; #while (j:n) #declare L= VDist(ico[i],ico[j]); #if(L&lt;1adoIco+0.1) #declare icosi[nicos]=ico[i]+0.5*(ico[j]-ico[i]); #write (Icf, Au", " ",vstr(3, icosi[nicos]," ",3,5),"\n") sphere{(icosi[nicos], 0.25 pigment{color Red}} #declare nicos=nicos+1; #end #declare j=j+1; #end #declare i=i+1; #end</pre>
---	---



### The truncated icosidodecahedron from the truncated icosahedron

It is also known as great rhombicosidodecahedron and it is the largest Archimedean solid. The structure is built by 30 squares, 20 hexagons and 12 decagons. It has 120 vertices and 180 edges. It can be constructed by dividing the icosidodecahedron edges in three equal parts and a further translation along a perpendicular vector of the formed hexagons (i.e., related dodecahedron vertices). However, we chosen to start from a truncated icosahedron (figure 7), whose hexagonal faces were translated along the dodecahedron vertices. The selection of hexagonal faces implies to calculate the dot product among the face vertices and its perpendicular vector. It was determined that a value of circa 0.875 (i.e., k = 0.875) for the dot product allows to select the hexagonal faces. The translation vector k was calculated as circa 1.40 times the hexagon edge (Williams, 1979). The described algorithm is given in terms of formulas 2 and 3. See figure S1(annex) for more geometrical details.

$$\vec{V}_p = \vec{P}_{dode} \tag{2}$$

$$\vec{Qn}_{Trunc-icosi} = \vec{Pn}_{hexagon} + k\vec{P}_{dode}$$
(3)

Where  $\overrightarrow{Pn}_{hexagon}$  corresponds with hexagonal faces of truncated icosahedron. Formula 2 indicates the magnitude of each perpendicular vector, that is along one related position vector of the dodecahedron.

Formula 3 stands for the translation of the obtained hexagonal faces  $(\overrightarrow{Qn}_{Trunc-icosi})$ .

In Box 10 the programmed code is included, and it contains in the last part the algorithm to select and translate vertices. The structure is displayed in figure 10.

Figure 10. Truncated icosidodecahedron or great rhombicosidodecahedron. The hexagonal faces of the truncated icosahedron are translated along perpendicular vectors, it means along the dodecahedron vertices. The truncated icosahedron is displayed in blue color.





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#### The rhombicuboctahedron from a cube

The rhombicuboctahedron is constituted by 18 square faces, 8 triangular faces and 24 vertices, being the same edge length in both type of faces. It is an Archimedean solid formed by the outward translation of the vertices forming each square face of a cube. The translation of each square face is along its respective perpendicular vectors (they can be calculated using the formula 4). In the case of one centered cube with an edge of acube, <acube/2,0,0>, <-acube/2,0,0>, <0,acube/2,0>, <0,-acube/2,0>, <0,0,acube/2> and <0,0,-acube/2> represent perpendicular vectors to each square face. The magnitude of the perpendicular vectors can be analytically calculated and it corresponds with the acube/sqrt(2) value (i.e. k = 0.7071\*acube in formula 5). We calculate numerically the k value by adding up successively a fraction of a pair of perpendicular vectors (for example <1,0,0> and <0,0,-1>) to the same cube vertex and attesting that at certain translation, the distance among new created positions equals the cube edge. See supporting information (figure S1 in annex) for more details and the used code.

$$\vec{V}_p = (\vec{P3}_{cube} - \vec{P1}_{cube}) \otimes (\vec{P2}_{cube} - \vec{P1}_{cube})$$
(4)

$$\vec{Qn}_{Rhom} = \vec{Pn}_{cube} + k\vec{V}_p \tag{5}$$

Where  $\vec{Pn}_{cube}$  represent the position vectors of the nth vertex of a cube, and  $\vec{Qn}_{Rhom}$  are the position vectors of the translated vertices forming the



rhombicuboctahedron. Figure 11 contains a graphical explanation of the given formulas.

**Figure 11.** Rhombicuboctahedron obtained from a cube. All vertices of cube are translated along a perpendicular vector (Vp). Q position is obtained from translation of P position. The triangular faces are formed after the translation of the square faces of the parent cube (red color).



Source: Author's elaboration.

It is also worth to notice that rhombicuboctahedron can also be obtain from the dual of a cube, i.e., the octahedron. The triangular octahedron's faces must be translated b\*0.8660. Being *b* the length of the octahedron's edge (b = acube/sqrt(2), and *acube* the edge of the cube where the octahedron is inscribed). On the other hand, an angle of circa 1.23 radians is comprised between both perpendicular translation vectors, which originate from the octahedron's vertices. And the angle between the perpendicular vector and the octahedron's edge is of 0.9547 radians. The same proportion is found when we try to obtain the truncated cube from the cuboctahedron. A full deduction of this is included in the supporting information (figure S3 in annex).

The code given in Box 11 can be simplified by using the function Vperp\_ To\_Plane (V1, V2) where V1 and V2 are along the edges of the polyhedral face. This operation is given by the formula 4. However, we considered important to provide the readers with code that is easy to visualize and to be related to the above given formulas 4 and 5.

#### The truncated cube from a cuboctahedron

In addition to the irregular truncation of the cube edge (Box 3), in this section is explained another form to truncate the cube. The truncated cube is built by 8 triangular and 6 octagonal faces, linking 24 vertices. It can be obtained by the selection and the outward translation of the triangular faces of the cuboctahedron. This operation is simplified by knowing that position vector of each cube's vertex is perpendicular to triangular faces of the cuboctahedron. The procedure to translate each triangular face of the cuboctahedron is given in formula 6, where three vertices of the truncated cube are obtained by adding one position vector of the cube to three vertices of the cuboctahedron. This operation is repeated to translate outward all 8 triangu-



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Box 11. POV-Ray code to make a rhombicuboctahedron	#end
with edge of 1	#declare i=i+1;
// Insert here the last definition of libraries, // light_	#end
source, camera, and background	//Translation of square faces
#declare acube=1; // cube edges length	#fopen out "Rhombicuboctahedron.xyz" write
#declare Pos= arrav[8]: // cube positions	#declare i=0:
#declare Pos= array[8]; // cube positions #declare Rho= array [24]; // Rhombicuboctahedron	#declare n=24;
vertices	#while(i <n)< td=""></n)<>
// Insert here cube positions given as (±acube/2, ± acube/2,	#declare Rho[i]=Rho[i]+ 0.7071*acube
$\pm$ acube/2)	*vnormalize((Center[i/4]));
// Calculation of center of cube faces (perpendicular	#declare Rho[i+1]=Rho[i+1]+0.7071*acube
// vectors)	*vnormalize((Center[i/4]));
#declare i=0;	#declare Rho[i+2]=Rho[i+2]+0.7071*acube
#declare Center=array[6];	*vnormalize((Center[i/4]));
#declare counter=0;	#declare Rho[i+3]=Rho[i+3]+0.7071*acube
#declare n=8;	*vnormalize((Center[i/4]));
#declare j=1;	#write (out "Au" " "wetr(3 Rho[i] " " 3 5) "\n")
#while (j <n)< td=""><td><pre>write (out, "Au", " "vstr(3, Rho[i, " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+1], " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+2], " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+3], " ",3,5),"\n")</pre></td></n)<>	<pre>write (out, "Au", " "vstr(3, Rho[i, " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+1], " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+2], " ",3,5),"\n") #write (out, "Au", " ", vstr(3, Rho[i+3], " ",3,5),"\n")</pre>
#declare L= VDist(Pos[0],Pos[j]);	#write (out, Au, , , vstr(3, Hio[i+1], , 3, 5), (ii)
#if(L=acube*sqrt(2))	#write (out, Au, ", vstr(3, Ruo[i+2], ", 3, 5), (ii) $\#$ write (out, "Au," ", "wrtr(3, Rho[i+3], ", 3, 5), "\n")
#declare Center[counter]= Pos[0]+(Pos[j]-Pos[0])/2;	#declare i= i+4;
#declare Center[counter]= -1*Center[counter];	#end
#declare counter=counter+1;	" end
#end	// Drawing the model with spheres
#declare j=j+1;	#declare h=pow(10,-3);
#end	#declare i=0:
"end	#while (i <n-1)< td=""></n-1)<>
//selecting vertices to translate on each square face	sphere {Rho[i],0.2 texture { pigment { color Red} } }
#declare i=0;	#declare j=i+1;
#declare lado= acube*sgrt(2)/2;	#while(j <n)< td=""></n)<>
#declare coun=0	#if (VDist(Rho[i],Rho[j]) <acube+2*h &<="" td=""></acube+2*h>
#while (i <counter)< td=""><td>VDist(Rho[i],Rho[j])&gt;acube-2*h)</td></counter)<>	VDist(Rho[i],Rho[j])>acube-2*h)
#declare j=0;	cylinder {Rho[i], Rho[j], 0.1 texture {pigment { color
#while (j <n)< td=""><td>Yellow } } }</td></n)<>	Yellow } } }
#if(VDist(Center[i],Pos[j])= lado)	#end
#declare Rho[coun]=Pos[j];	#declare j=j+1;
#declare coun=coun+1;	#end
#end	#declare i=i+1;
#declare j=j+1;	#end
, ,,	··

lar faces constituting the cuboctahedron. The magnitude of perpendicular translation (k vector magnitude) was numerically calculated and it is defined as acube\*sqrt(3)/2 (i.e., acube\*0.8660). Figure 12 includes the discussed structure of the truncated cube, and Box 12 has the implemented code.

$$\vec{P}_{Trun-Cube} = \vec{P}_{cuboctahedron} + k\vec{P}_{Cube}$$
(6)

**Figure 12.** Making a truncated cube from a cuboctahedron. Each triangular face of the cuboctahedron is translated along one diagonal of the cube. The translated vertices constituting the truncated cube are linked by cylinders featured in green color. Thin red cylinders correspond with the cube.



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#### The truncated cuboctahedron from a truncated cube

It is also named as great rhombicuboctahedron (Williams, 1979), and it is constituted by 12 square faces, 8 hexagonal faces, 6 octagonal faces and 48 vertices (figure 13). It can be built by the truncation of triangular faces of the truncated cube in three equal parts to generate the hexagonal faces (formulas 2 and 3). However, further inward translation of hexagons along the perpendicular vectors (cube vertices is necessary to obtain a truncated cuboctahedron with equal edges. The algorithm to construct this Archimedean solid includes a conditional to verify that the edges of the hexagonal faces (one third of the cuboctahedron) equal the distance among neighboring hexagonal faces. In formula 9, the perpendicular vector has a magnitude 0.985 times the edge of the cuboctahedron, and the sign indicates an inward translation. Moreover, each perpendicular vector to one hexagonal face is along the position vector of respective cube vertices. See Box 13 for the code.

$$\vec{P}_{Trun-Cuboctahedron} = \vec{P}_{Trun-Cube-hex} - k * \vec{P}_{Cube}$$
(7)



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**Figure 13.** Truncated cuboctahedron from a truncated cube. The triangular faces of the truncated cube are truncated in three equal parts and the new hexagonal faces (orange/red sticks) are translated along vectors oriented on the diagonal of the cube indicated in red color. The translated vertices constituting the truncated cuboctahedron are linked by cylinders in orange color.



Source: Author's elaboration.

Box 13. Pov-Ray Code To Make a Truncated Cuboctahedron // Insert here the last definition of libraries, // light_source, camera, and background #declare acube=1; // cube edges length #declare cuboc= array[8]; // cube positions #declare cuboc= array [12]; // Cuboctahedron vertices // Insert here code to make the truncated cube included in Box 12. TC[24] represents the positions of truncated cube. #declare kon=0; #declare kon=0; #declare kon=0; #declare i=0; #while (i <nsele) #declare vi= TC[j]-TC[i]; #declare k=j+1; #while (i<nsele) #declare V1= TC[j]-TC[i]; #declare V2=TC [k]-TC[i]; #declare Dd1= VDist(TC [i],TC[j]); #declare Dd1= VDist(TC [i],TC[j]); #declare angulo= VAngleD(V1,V2); //finding edges with a common vertex; edge equals sqrt(2)/2 #if((Dd&lt;0.8 &amp; Dd)-0.7) &amp; (Dd1&lt;0.8 &amp; Dd1&gt; 0.7) &amp; (angulo&gt;59 &amp; angulo&lt;61)) #declare hexa1[kon]=TC[i]+(TC[i]-TC[i])/3; #declare hexa1[kon]=TC[i]+2*TC[k]-TC[i])/3; #declare hexa1[kon]=TC[i]+(TC[k]-TC[i])/3; #declare hexa1[kon+1]=TC[i]+2*(TC[k]-TC[i])/3; #declare hexa1[kon+2]=TC[j]+(TC[k]-TC[j])/3; #declare hexa1[kon+3]=TC[i]+(TC[k]-TC[j])/3; #declare hexa1[kon+3]=TC[i]+(TC[k]-TC[j])/3; #declare hexa1[kon+4]=TC[j]+2*(TC[k]-TC[j])/3; #declare hexa1[kon+4]=TC[j]+ 2*(TC[k]-TC[j])/3;</nsele) </nsele) 	<pre>#declare kon=kon+6; #end #declare k=k+1; #end #declare j=j+1; #end //Selection of hexagons and normal vectors to translate them #declare Inex= array[480]; #declare Inex= array[480]; #declare Inex= array[480]; #declare Inex= array[480]; #declare Inex= array[480]; #declare Inex= array[480]; #declare i=0; #while(i&lt;48) #declare i=0; #while(i&lt;48) #if (vdot(hexa1[i],Pos[j])&lt;(1+0.2) &amp; vdot(hexa1[i], Pos[j])&gt; (1-0.2)) #declare Thex[konter]=hexa1[i]-0.985* ladoCuboc *vnormalize(Pos[j])); sphere {Thex[konter], 0.3 pigment {rgb &lt;1,0,0&gt;}} #write (TrCubocta,"H", ",vstr(3, Thex[konter ]," ",3,5),"\n") #declare konter=konter+1; #end #declare i=i+1; #end</pre>
---	---

#### The snub cube from the rhombicuboctahedron

This Archimedean solid is comprised by 6 squares, and 32 equilateral triangles. It has 24 vertices and 60 edges. The rotation of the square faces of the rhombicuboctahedron is included in the algorithm given in Box 14. Depending on the rotation (clockwise or counter-clockwise) a pair of enantiomers are produced (it is a chiral structure) (Ball and Coxeter, 1987). If a rotation of circa 16 degrees is applied on each square face, then the square faces of the rhombicuboctahedron



seem to rotate in contrary directions when they are seen perpendicular to those square faces. In figure 14, the structure of the snub cube is provided.

**Figure 14.** Snub cube from a rhombicuboctahedron. The square faces of the rhombicuboctahedron (blue color) are rotated with respect to perpendicular vectors passing through the cube faces. The rotated vertices constituting the snub cube are linked by cylinders (green color). Left structure corresponds with a counter-clockwise rotation. Both enantiomers are related by a mirror symmetry operation.



Source: Author's elaboration.

```
Box 14. POV-Ray code to make a snub cube with edge length
of 1
// Insert here the last definition of libraries,
// light_source, camera, and background
                          // cube edges length
#declare acube=1;
#declare Pos= array[8];
                           // cube positions
#declare cuboc= array [12]; // Cuboctahedron vertices
// Insert here the rhombicuboctahedron included in Box 11.
    Center[counter] represents the center of cube faces. Rho
    is the array containing 24 vertices of
    rhombicuboctahedron
// Selection of square faces and their rotation
    #write (SnubCub,"24","\n")
#write (SnubCub,"","\n")
#declare konter3=0;
#declare angulo= 16.47;
#declare i=0;
#while(i<24) // vertices
#declare j=0;
#while (j<6) // centers
#if (vdot(Rho[i],Center[j])<(0.6036+0.1) & vdot(Rho[i],
    Center[j] )> (0.6036-0.1) )
 #declare Snubcu[konter3]= vaxis rotate(Rho[i], Center[i],
angulo);
   sphere {Snubcu[konter3], 0.1 pigment {color Blue} }
  #write (SnubCub,"Au", " ",vstr(3, Snubcu[konter3 ],"
",3,5),"\n")
    #declare konter3=konter3+1;
#end
  #declare j=j+1;
#end
 #declare i=i+1;
#end
```

It is important to note that we are using the dot product to select square faces of the rhombicuboctahedron. Rotations are carried out by using the



command axis\_rotate (V1, V2, angle), being V1 the rhombicuboctahedron vertices array and V2 the centers array. The twist angle was determined numerically, and it is of circa 16.47° (WolframMathworld, http://mathworld. wolfram.com/SnubCube.html). On the other hand, the calculated dot product among the perpendicular vector and one vertex of the rhombicosidode-cahedron was calculated as 0.6036\*acube<sup>2</sup>. This value is included in our algorithm to select vertices forming a square face and to rotate them with respect to the related perpendicular vector.

#### The rhombicosidodecahedron from the dodecahedron

This structure has been found comprising the structure of one I- $Au_{144}$  cluster, and it represents a distorted 60-shell atoms where the gold atoms are separated and they are linked to an inner gold core (Tlahuice-Flores *et al.*, 2013). The rhombicosidodecahedron is an Archimedean solid built by 20 triangles, 30 squares and 12 pentagons. It has 60 vertices and 120 edges. To generate it, we selected each pentagonal face of dodecahedron (12 pentagonal faces) and translated it outwards along a perpendicular vector. The perpendicular vectors are given by the dual of dodecahedron (icosahedron) and their magnitude was calculated as circa 0.951 times the dodecahedron edge length. See figure 15 for an illustration of the structure and Box 15 for the code.

**Figure 15.** Rhombicosidodecahedron obtained from a dodecahedron. The pentagonal faces of the dodecahedron (blue color) are translated with respect to perpendicular vectors. The triangular faces are formed when all the inter-face distances equal the pentagon edges length.



Source: Author's elaboration.

#### The snub dodecahedron from the rhombicosidodecahedron

The snub dodecahedron is also known as snub icosidodecahedron. It has 12 pentagons, and 80 equilateral triangles, and its 150 edges join the 60 vertices constituting him. It can be obtained from the rotation of the pentagonal faces of the rhombicosidodecahedron in a similar way that the snub cube is made from the rhombicuboctahedron. The rotation of the pentagonal faces can be done both clockwise and counter-clockwise orientation, resulting in two structures related by a mirror symmetry operation. If the edge of this solid is the unit, then a rotation of 18.2158° is necessary to change the square faces by



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sphere {Rho[konter], 0.3 pigment {rgb <1,0,0>} } Box 15. Pov-Ray code to make a rhombicosidodecahedron #write (rhombicosidode,"Au", " ",vstr(3, Rho[konter ]," with edge length of 1 // Insert here the last definition of libraries, ",3,5),"\n") #declare konter=konter+1; // light source, camera, and background // cube edges length #declare acube=1; #end #declare j=j+1; #declare Pos= array[8]; // cube positions #end #declare cuboc= array [12]; // Cuboctahedron vertices #declare i=i+1; // Insert here the dodecahedron and icosahedron arrays. #end // spheres Model #declare adode= 1 : #declare h=0.1: #declare i=0: // dode[n] contains dodecahedron vertices #while (i<60) // Selecting and moving pentagonal faces sphere {Rhom[i],0.1 texture { pigment { color Red} } } #fopen rhombicosidode "rhombicosidodecaedro.xyz" write #declare j=i+1 ; #write (rhombicosidode,"60","\n") #while(j<60) #write (rhombicosidode,"","\n") #if (VDist(Rhom[i],Rhom[j])<adode+2\*h & #declare konter=0: VDist(Rhom[i],Rhom[j])>adode-2\*h) #declare i=0; cylinder {Rhom[i], Rhom[j], 0.05 texture { pigment { color #while(i<20) Yellow} finish { phong 0.0 reflection{ 0.00 metallic #declare j=0; 0.00}}} #while (j<12) #end #if (vdot(vnormalize(dode[i]), vnormalize(ico[j]))> (0.75) & #declare j=j+1; vdot(vnormalize(dode[i]), vnormalize(ico[j]))< (1.0)) #end // dot product among one vertex and the center of one #declare i=i+1; face #end #declare Rho[konter]=dode[i]+ 0.95088\*adode \*vnormalize((ico[j])); // magnitude of the perpendicular vector

triangular ones (Weisstein, 2020; WolframMathworld, http://mathworld.wolfram.com/ SnubDodecahedron.html). Recently, we have calculated one hollows  $Au_{60}$  cluster corresponding with a perfect snub dodecahedron. It means that modeling of Archimedean can be used to investigate structures with relevance in chemistry (Jacobo-Fernández and Tlahuice-Flores, 2021).

Figure 16 contains the rhombicosidodecahedron structure. Box 16 contains the Pov-Ray code of the snub dodecahedron.

**Figure 16.** Snub dodecahedron from the rhombicosidodecahedron. Making a snub dodecahedron from rotation of pentagonal faces of the rhombicosidodecahedron. The cylinders in blue correspond with the rhombicosidodecahedron. The rotation of pentagonal faces transforms the square in triangular faces (green color). To simplify the view, the edges of rhombicosidodecahedron are displayed as thin cylinders.





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Box 16. Pov-Ray code to make snub dodecahedron with	<pre>#end</pre>
edge length of 1	#declare j=j+1;
//Insert here code from Box 15	#end
#fopen SnubD "SnubRhombicosidode.xyz" write	#declare i=i+1;
#declare SnubRho= array [120];	#end
#write (SnubD,"60","\n")	#declare n=0;
#write (SnubD,"","\n")	#declare j=0;
<pre>#write (JHubD, ', 'H') #declare konter5=0; #declare angulo=18.215828464309; #declare i=0; #while(i&lt;60) // vertices #declare j=0; #while (j&lt;12) // centers #if (vdot(vnormalize(Rhom[i]), vnormalize(ico[j]))&gt;(0.75) &amp; vdot(vnormalize(Rhom[i]), vnormalize(ico[j]))&gt;(1)) #declare SnubRho[konter5]= vaxis_rotate(Rhom[i], ico[j], angulo); sphere {SnubRho[konter5], 0.06 pigment {color Blue} } #write (SnubD,"Au", " ",vstr(3, SnubRho[konter5],"</pre>	<pre>// spheres Model #declare h=0.2; #declare i=0; #while (i&lt;60) #declare j=i+1; #while(j&lt;60) #if (VDist(SnubRho[i],SnubRho[j])&gt;adode+2*h &amp; VDist(SnubRho[i],SnubRho[j])&gt;adode-2*h) cylinder {SnubRho[i],SnubRho[j], 0.05 texture { pigment {color Green} finish {phong 0.0 reflection{ 0.00 metallic 0.00} } } } #end #declare j=j+1; #end #declare i=i+1; #end</pre>

# Conclusions

The addressed project was carried out by undergraduate students, and it included the planning, and election of the shortest paths to code the 13 Archimedean solids. This study represents an improvement in their programming level where the use of macros was mandatory to reduce the size of the delivered code. The students were involved in the study of the geometrical relationships of regular and irregular solids, and these let us obtain a more intuitive view during the modeling/construction of the irregular solids. We do not demerit the use of plastic models, but that approach is limited in the size of studied compounds.

Among all proposed/coded algorithms included in this publication, the irregular truncation of edges of a regular solid, let us obtain 3 of the 13 Archimedean solids. However, other algorithms to select faces, to translate and to rotate them were necessary. This resulted in the generation of new algorithms that were coded in an object-oriented language (Pov-Ray).

Regarding the granted capabilities of students, this project improved their spatial depth and requested of their creativity. They were involved during the decision-making process to reach the final goal: the programming of 13 Archimedean solids.

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# Annex. Use of Macros in POV-Ray codes\*

Figure S1. Icosidodecahedron geometrical features.

Figure S2. Rhombicuboctahedron calculation of the k value from cube.

Figure S3. Rhombicuboctahedron deduction of k value from octahedron.

The use of macros is helpful in POV-Ray codes. A macro is declared by using an identifier, and a list of parameters. Its syntax is as follows:



Macros need to be declared before they can be used. The manner to invoke them is as follows:

Macro\_identifier (parameters list)

The next example is provided to facilitate the understanding of macros.

```
#macro Enlaces (first, final, Ve1, distan, kolor)
    // printing bonds as cylinders
    #declare i=first;
    #while (i< final-1)
    #declare j=i+1;
    #while (j< final)
    #declare L1= VDist( Ve1[i], Ve1[j]);
    #if(L1< a* (distan) +0.01)
        cylinder{ Ve1[i], Ve1[j] 0.05 pigment{color kolor} }
    #end
    #declare j=j+1;
    #end
#declare i=i+1;
#end</pre>
```

It can be used to calculate the edges of a solid as cuboctahedron.

<sup>\*</sup> Annex related to macros, deduction of magnitude of the translation vectors of rhombicuboctahedron and truncated icosidodecahedron.



```
POV-Ray Code to make a cuboctahedron
// Insert here the last definition of libraries,
// light source, camera, and background
#declare acube=2/sqrt(2); //cube edges length
#declare Pos= array[8];
                          // cube positions
#declare cuboc= array [12]; // cuboctahedron vertices
// Cube positions
#declare Pos[0]= <acube/2, acube/2, acube/2>;
#declare Pos[1]= <-acube/2, -acube/2, -acube/2>;
#declare Pos[2]= <-acube/2, acube/2, acube/2>;
#declare Pos[3]= <acube/2, -acube/2, acube/2>;
#declare Pos[4]= <acube/2, acube/2, -acube/2>;
#declare Pos[5]= <-acube/2, -acube/2, acube/2>;
#declare Pos[6]= <-acube/2, acube/2, -acube/2>;
#declare Pos[7]= <acube/2, -acube/2, -acube/2;</pre>
#fopen cuboct "cuboctahedron.xyz" write
// This block is to calculate the distances among vertices
// and to define edges
//Calculating the center of cube edges
  #declare i=0;
  #declare ncub=0:
  #declare n=8:
  #while (i<n-1)
   #declare i=i+1:
    #while (j<n)
     #declare L= VDist(Pos[i],Pos[j]);
      #if(L< acube+0.1)</pre>
       #declare cuboc[ncub]=Pos[i]+0.5*(Pos[j]- Pos[i]);
        sphere{cuboc[ncub], 0.25 pigment{color Red}}
#write (cuboct,"Au", " ",vstr(3, cuboc[ncub]," ",3,5),"\n")
        #declare ncub=ncub+1;
      #end
     #declare j=j+1;
     #end
    #declare i=i+1;
   #end
```

To show the edges, the macro is invoked as follows. **Enlaces** (0, 11, cuboc, 1, Green).

### The truncated icosidodecahedron

To select the hexagonal faces of the truncated icosahedron, it was necessary to calculate the dot product among the position vectors of the dodecahedron (cyan spheres in figure S1) and the position vectors of vertices of the truncated icosahedron (orange vectors).

With respect to the magnitude of the translation vector (k) it was necessary to subtract the relation of the distance from the origin to the center of hexagonal faces of truncated icosahedron and trun-cated icosidodecahedron. That relationship was found in the reference 22 (Weisstein, 2020).



Figure S1. Truncated icosidodecahedron from a truncated icosahedron.



Note: Both Archimedean solids have hexagonal faces, in such manner that the translation of the hexagonal faces of the truncated icosahedron produces the truncated icosidodecahedron.

# Rhombicuboctahedron calculation of the magnitude (k) of the perpendicular vector

To obtain the magnitude of the perpendicular vector (k) to the cube faces, it was necessary to make a code to translate the cube vertices by a fraction. In the following box is included the used code.



**Figure S2.** Illustration of the calculation of the magnitude (k) of the displacement vector applied to cube vertices to obtain the rhombicuboctahedron. RC[0] and RC[8] are obtained by translating one vertex of the cube along perpendicular vectors to square faces.





In figure S2, the blue triangle can be used to analytically obtain the magnitude of the translation vector (k).

Then

$$k^2 + k^2 = acube^2$$

$$k = \frac{acube}{\sqrt{2}}$$

# Rhombicuboctahedron deduction of the magnitude (k) of the perpendicular vector

Figure S3. Illustration of the calculation of the magnitude of the displacement vector applied to octahedron vertices to obtain the rhombicuboctahedron.



As mention in the main manuscript, the Rhombicuboctahedron can be obtain from both the cube and its dual, the octahedron. In each case we have to translate the faces a certain distance (k). In the case of the octahedron, this length is  $b^*0.8660$ , being b the edge of the octahedron. In the following, we explore how did we deduce this.

In the figure S3 the blue dot represents one of the octahedron's vertices. As we can see, 2 vectors come out from the octahedron's vertex (there are 4 vertices of the Rhombicuboctahedron for each octahedron's vertex but for simplicity issues we just consider two). These two vectors are the "translation vectors" from the octahedron's vertex to its rhombicuboctahedron's vertices. So, the distance between the two reddots (representing Rhombicuboctahedron's vertices) must be the same as the edge of the octahedron

At first we give these vectors a length of 1; which is the default value given by Pov-Ray with the function *VPerp\_To\_Plane* (*V*1, *V*2). This arbitrary value is just given because we aren't interest-ed in the length of the vectors yet, but in the angle between them.



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The program shows that the angle between the vectors is 70.5369° and the other angles are 54.7315°@ each. Given this information, we can use the sine rule in order to calculate the length of the vectors.

$$\frac{b}{\sin(1.2311 \text{ radians})} = \frac{k}{(0.95245)}$$

Being b the edge of the octahedron and rhombicuboctahedron rhombicuboctahedron, and k the length of the translation vector.

$$k = \frac{b \sin(0.95245)}{\sin(1.2311 \ radians)}$$

k = b(0.8659)

Coordinates of the rhombicuboctahedron obtain by the translation of octahedron's faces:

1	-0.70692	0.70692	1.70692	13	-1.70692	0.70692	0.70692
2	0.70692	0.70692	1.70692	14	-1.70692	0.70692	-0.70692
3	-0.70692	-0.70692	1.70692	15	-1.70692	-0.70692	0.70692
4	0.70692	-0.70692	1.70692	16	-1.70692	-0.70692	-0.70692
5	0.70692	1.70692	0.70692	17	-0.70692	-1.70692	0.70692
6	0.70692	1.70692	-0.70692	18	0.70692	-1.70692	0.70692
7	-0.70692	1.70692	0.70692	19	-0.70692	-1.70692	-0.70692
8	-0.70692	1.70692	-0.70692	20	0.70692	-1.70692	-0.70692
9	1.70692	-0.70692	0.70692	21	0.70692	0.70692	-1.70692
10	1.70692	0.70692	0.70692	22	0.70692	-0.70692	-1.70692
11	1.70692	-0.70692	-0.70692	23	-0.70692	0.70692	-1.70692
12	1.70692	0.70692	-0.70692	24	-0.70692	-0.70692	-1.70692

